## Personalized Instruction of Physical Skills with a Social Robot

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### Social Robotics Lab

#### **Alexandru Litoiu**

- 3<sup>rd</sup> year PhD Candidate
- Social Robotics Lab, Yale University
- Interested in building robots that can coach physical tasks
- Started project a couple of months ago
- o Canadian!

## A Novice Tennis Serve



## An Expert Tennis Serve



## An Expert Tennis Serve – Slow Motion



# Socially Assistive Robots for Coaching Physical Tasks

How do we deliver advice to effectively induce a transformation from incorrect human movements into correct human movements?

- Help children to become more physically proficient
- Children that are more physically proficient are more likely to be more physically active [1] [2]
- Assist rehabilitation patients to perform complex motor tasks

<sup>[1]</sup> Wrotniak, Brian H., et al. "The relationship between motor proficiency and physical activity in children." Pediatrics 118.6 (2006): e1758-e1765.

<sup>[2]</sup> Barnett, Lisa M., et al. "Childhood motor skill proficiency as a predictor of adolescent physical activity." Journal of Adolescent Health 44.3 (2009): 252-259.

#### **Robotic Orthoses**



### **Socially Assistive Robots**





## Application Domain: Teaching Children to Shoot a Basketball

#### Reliable supervisory signal

Clear score/no score

#### Simplified perception

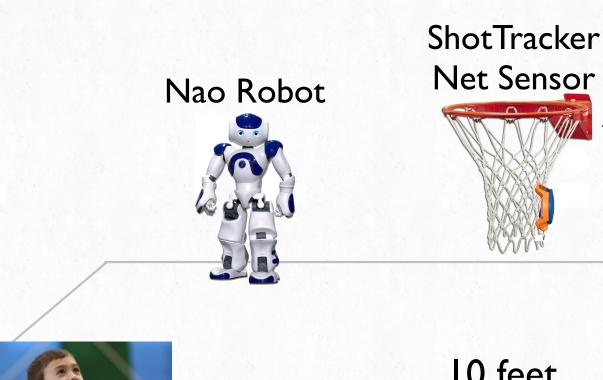
 Free throw from same spot – perception system stationary

#### Automated Coachability

- Repetitive motion enables system to learn and give recommendations
- Ball in hand do not need to change motion based on a pitch, i.e. baseball



### **Experimental Setup**





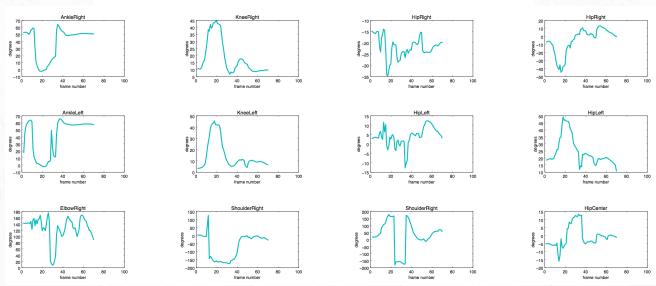
10 feet

**Kinect** Sensor

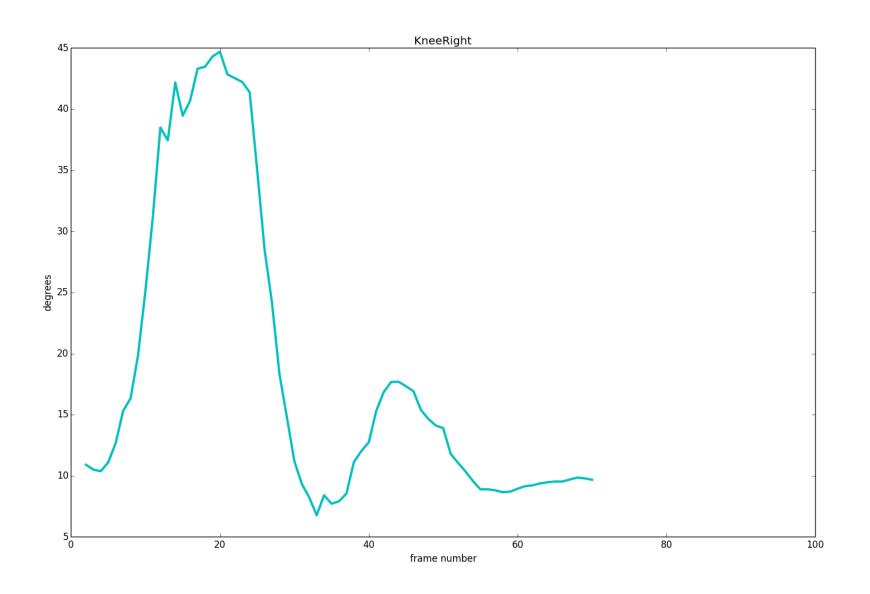


## Perception of Joint Angle Time Series Using Kinect

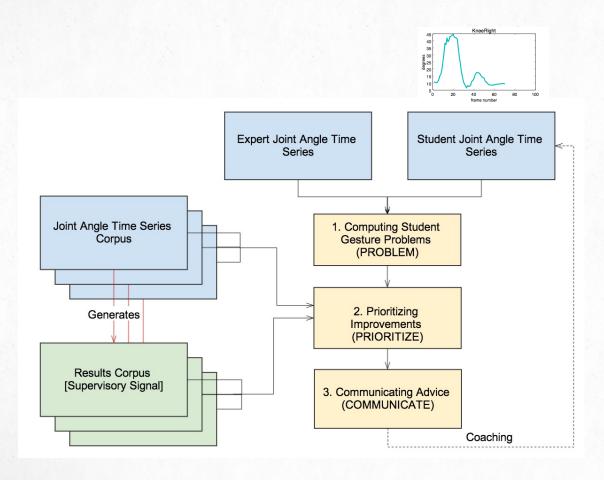




### Right Knee Time Series

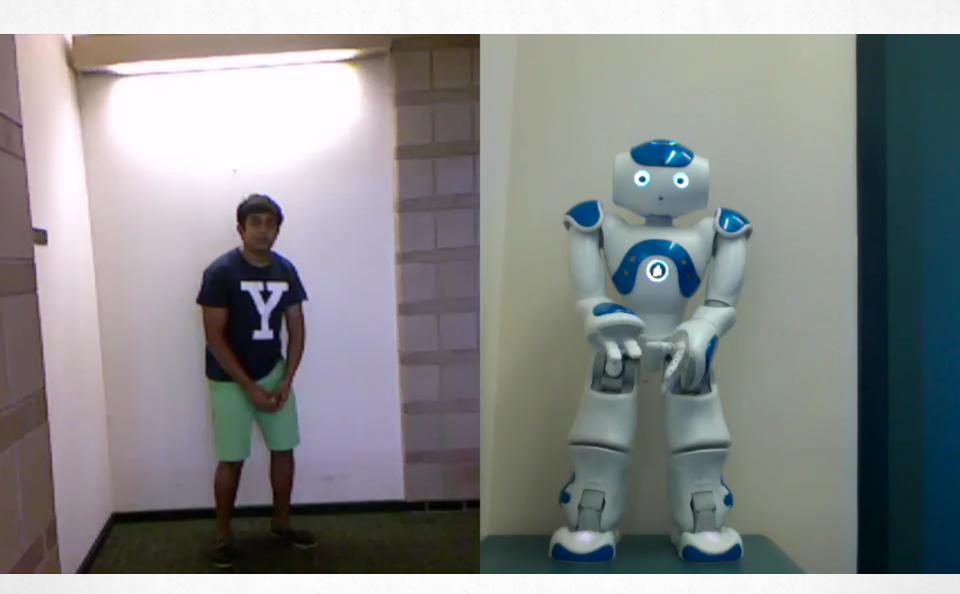


# A First Pass Approach For Physical Skills with Supervisory Signals



- Converge your shot to a reference trajectory
- Understand the participant and be useful, as quickly as possible

# Communicating Advice – Demonstrations



### Summary

- How do we deliver advice to effectively induce a transformation from incorrect human movements into correct human movements?
  - Help children to become more active
  - Help rehabilitate recovering stroke and spinal cord injury patients
- Started creating a system to coach supervised motions such as basketball
  - Created a PROBLEM module
  - Collected data for and investigating machine learning approaches for PRIORITIZE
  - In advanced stages of creating demonstration COMMUNICATION module

### Thank You